

## TOTALLY UMBILICAL PSEUDO-SLANT SUBMANIFOLDS OF RIEMANNIAN PRODUCT MANIFOLDS

MERAJ ALI KHAN, FALLEH R. AL-SOLAMY, AMIRA A. ISHAN

**ABSTRACT.** In the present paper we have study totally umbilical pseudo-slant submanifolds of Riemannian product manifolds via Riemannian curvature tensor and finally obtained a classification for the Totally umbilical pseudo-slant submanifolds of Riemannian product manifolds.

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### 1. INTRODUCTION

The notion of slant submanifolds of an almost Hermitian manifold was introduced by B.Y. Chen [3]. These submanifolds are the generalization of both holomorphic and totally real submanifolds of an almost Hermitian manifold with an almost complex structure  $J$ . The notion of semi-slant submanifolds of Kaehler manifolds was initiated by N. Papaghuic [8]. Bi-slant submanifolds of an almost Hermitian manifold were introduced as a natural generalization of semi-slant submanifolds and anti-slant submanifolds by A. Carriazo [1]. The class of bi-slant submanifolds includes complex, totally real and CR-submanifolds. But the name anti-slant seems it has no slant factor, so B. Sahin [4] named these submanifolds as pseudo-slant submanifolds and studied these (pseudo-slant) submanifolds in Kaehler setting for their warped product. B. Sahin [5] studied semi-invariant and totally umbilical semi-invariant submanifolds of Riemannian product manifolds and a step forward M. Atceken [7] defined slant and bi-slant submanifolds in the setting of Riemannian product manifolds and in particular he studied semi-slant submanifolds, since pseudo-slant submanifolds are special cases of bi-slant submanifolds then it will be worthwhile to study the pseudo-slant submanifolds in this setting. The purpose of this paper is to study totally umbilical pseudo-slant submanifolds of Riemannian product manifolds.

## 2. PRELIMINARIES

Let  $(M_1, g_1)$  and  $(M_2, g_2)$  be the Riemannian manifolds with dimension  $m_1$  and  $m_2$  respectively, and  $M_1 \times M_2$  be Riemannian product manifold of  $M_1$  and  $M_2$ . We denote projection mapping of  $T(M_1 \times M_2)$  onto  $TM_1$  and  $TM_2$  by  $\sigma_*$  and  $\pi_*$  respectively. Then we have  $\sigma_* + \pi_* = I$ ,  $\sigma_*^2 = \sigma_* \pi_*^2 = \pi_*$  and  $\sigma_* \circ \pi_* = \pi_* \circ \sigma_* = 0$ , where  $\star$  mean derivatives.

Riemannian metric of the Riemannian product manifold  $M = M_1 \times M_2$  is defined by

$$g(X, Y) = g_1(\sigma_*X, \sigma_*Y) + g_2(\pi_*X, \pi_*Y)$$

for any  $X, Y \in T\bar{M}$ . If we set  $F = \sigma_* - \pi_*$  then  $F^2 = I$ ,  $F \neq I$  and  $g$  satisfies condition

$$g(FX, Y) = g(X, FY)$$

for any  $X, Y \in T\bar{M}$  thus  $F$  defines an almost Riemannian product structure on  $\bar{M}$ . We denote Levi-Civita connection on  $\bar{M}$  by  $\bar{\nabla}$ , then the covariant derivative of  $F$  is defined as

$$(\bar{\nabla}_X F)Y = \bar{\nabla}_X FY - F\bar{\nabla}_X Y,$$

for any  $X, Y \in TM$ . We say that  $F$  is parallel with respect to the connection  $\bar{\nabla}$  if we have  $(\bar{\nabla}_X F)Y = 0$ . Here from [10], we know that  $F$  is parallel, that is,  $F$  is Riemannian product structure.

Let  $\bar{M}$  be a Riemannian product manifold with Riemannian product structure  $F$  and  $M$  be a immersed submanifold of  $\bar{M}$ , we also denote by  $g$  the induced metric tensor on  $M$  as well as on  $\bar{M}$ . If  $\bar{\nabla}$  is the Levi-civita connection on  $\bar{M}$ , then the Gauss and Weingarten formulas are given by respectively, as

$$\bar{\nabla}_X Y = \nabla_X Y + h(X, Y) \tag{1}$$

$$\bar{\nabla}_X V = -A_V X + \nabla_X^\perp V \tag{2}$$

for any  $X, Y \in TM$  and  $V \in T^\perp M$ , where  $\nabla$  is the connection on  $M$  and  $\nabla^\perp$  is the connection in the normal bundle,  $h$  is the second fundamental form of  $M$  and  $A_V$  the shape operator of  $M$ . The second fundamental form  $h$  and the shape operator  $A_V$  are related by

$$g(A_V X, Y) = g(h(X, Y), V). \tag{3}$$

For any  $X \in TM$ , we can write

$$FX = fX + \omega X, \tag{4}$$

where  $fX$  and  $\omega X$  are the tangential and normal components of  $FX$ , respectively and for  $V \in T^\perp M$

$$FV = tV + nV, \quad (5)$$

where  $tV$  and  $nV$  are the tangential and normal components of  $FV$ , the submanifold  $M$  is said to be invariant if  $\omega$  is identically zero. On the other hand  $M$  is said to be an anti-invariant submanifold if  $f$  is identically zero.

The covariant derivatives of  $f$ ,  $\omega$ ,  $t$  and  $n$  is defined as

$$(\bar{\nabla}_X f)Y = \nabla_X fY - f\nabla_X Y \quad (6)$$

$$(\bar{\nabla}_X \omega)Y = \nabla_X^\perp \omega Y - \omega \nabla_X Y \quad (7)$$

$$(\bar{\nabla}_X t)V = \nabla_X tV - t\nabla_X V \quad (8)$$

$$(\bar{\nabla}_X n)V = \nabla_X^\perp nV - n\nabla_X^\perp V. \quad (9)$$

Using (1),(2) (4) and (6) we get

$$(\bar{\nabla}_X f)Y = A_{\omega Y}X + th(X, Y) \quad (10)$$

Let  $M$  be an immersed submanifold of a Riemannian product manifold  $\bar{M}$ , for each nonzero vector  $X$  tangent to  $M$  at a point  $x$ , we denote by  $\theta(x)$  the angle between  $FX$  and  $T_x M$ . The angle  $\theta(x)$  is called the slant angle of immersion.

Let  $M$  be an immersed submanifold of a Riemannian product manifold  $\bar{M}$ .  $M$  is said to be slant submanifold of Riemannian product manifold  $\bar{M}$  if the slant angle  $\theta(x)$  is constant which is independent of choice of  $x \in M$  and  $X \in TM$ .

Invariant and anti-invariant submanifolds are particular cases of slant submanifolds with angles  $\theta = 0$  and  $\theta = \pi/2$ . respectively, a slant submanifold which is neither invariant nor anti-invariant is called proper slant submanifold. The following characterization of slant submanifolds of Riemannian product manifolds is proved by M. Atceken [7].

**Theorem 1.** *Let  $M$  be an immersed submanifold of a Riemannian product manifold  $\bar{M}$ . Then  $M$  is a slant submanifold if and only if there exist a constant  $\lambda \in [0, 1]$  such that  $f^2 = \lambda I$ .*

*Moreover if  $\theta$  is the slant angle of  $M$ , then it satisfies  $\lambda = \cos^2 \theta$ .*

*Hence, for a slant submanifold we have the following relations which are consequences of above theorem*

$$g(fX, fY) = \cos^2 \theta g(X, Y) \quad (11)$$

$$g(\omega X, \omega Y) = \sin^2 \theta g(X, Y). \quad (12)$$

*for any  $X, Y \in TM$ .*

Now, we define the pseudo-slant submanifold of Riemannian product manifold  $\bar{M}$  as follows

**Definition 1.** A Submanifold  $M$  of a Riemannian product manifold  $\bar{M}$  is said to be pseudo-slant submanifold if there exist two orthogonal complemantry distribution  $D_\theta$  and  $D^\perp$  satisfying

(i)  $TM = D_\theta \oplus D^\perp$

(ii)  $D_\theta$  is a slant distribution with slant angle  $\theta \neq \pi/2$

(iii)  $D^\perp$  is anti-invariant distribution i.e.,  $FD^\perp \subseteq T^\perp M$ .

If  $\mu$  is invariant subspace under  $F$  of the normal bundle  $T^\perp M$ , then in the case of pseudo-slant submanifold, the normal bundle  $T^\perp M$  can be decomposed as

$$T^\perp M = \mu \oplus \omega D_\theta + \omega D^\perp.$$

A pseudo-slant submanifold  $M$  is said to be totally umbilical if

$$h(X, Y) = g(X, Y)H \tag{13}$$

where  $H = \frac{1}{n}(\text{trace } h)$ , called the mean curvature vector. For the totally umbilical pseudo-slant submanifold  $M$ , the equation (1)and (2) take the form

$$\bar{\nabla}_X Y = \nabla_X Y + g(X, Y)H \tag{14}$$

$$\bar{\nabla}_X V = -g(H, V)X + \nabla_X^\perp V. \tag{15}$$

The Riemannian curvature tensor is defined as

$$R(X, Y)Z = \bar{\nabla}_X \bar{\nabla}_Y Z - \bar{\nabla}_Y \bar{\nabla}_X Z - \bar{\nabla}_{[X, Y]} Z. \tag{16}$$

The equation of Coddazi for totally umbilical pseudo-slant submanifold  $M$  is given by

$$\bar{R}(X, Y, Z, V) = g(Y, Z)g(\nabla_X^\perp H, V) - g(X, Z)g(\nabla_Y^\perp H, V), \tag{17}$$

where  $\bar{R}(X, Y, Z, V) = g(\bar{R}(X, Y)Z, V)$  and  $X, Y, Z$  are vector fields on  $M$  and  $V \in T^\perp M$ .

It is easy to see that the Riemannian curvature tensor for Riemannian product manifolds satisfies the following properties

$$(a) \bar{R}(FX, FY)Z = \bar{R}(X, Y)Z \quad (b) F\bar{R}(X, Y)Z = \bar{R}(X, Y)FZ \tag{18}$$

By an externsic sphere we mean a submanifold of an arbitrary Riemannian manifold which is totally umbilical and has nonzero parallel mean curvature vector [9].

### 3. TOTALLY UMBILICAL PSEUDO-SLANT SUBMANIFOLDS

In this section, we will study a special class of pseudo-slant submanifolds which are totally umbilical. Throughout the section we consider  $M$  as a totally umbilical pseudo-slant submanifold of a Riemannian product manifold. Now we have the following theorem

**Theorem 2.** *Let  $M$  be a totally umbilical pseudo-slant submanifold of a Riemannian product manifold  $\bar{M}$  such that the mean curvature vector  $H \in \mu$ . Then one of the following statement is true*

- (i)  $M$  is totally geodesic.
- (ii)  $M$  is semi-invariant submanifold.

*Proof.* For  $V \in FD^\perp$  and  $X \in D_\theta$ , we have

$$\bar{\nabla}_X FV = F\bar{\nabla}_X V \quad (19)$$

using equations (14) and (15) the above equation becomes

$$\nabla_X FV + g(X, FV)H = -FXg(X, V) + F\nabla_X^\perp V.$$

Then by orthogonality of two distributions and the assumption  $H \in \mu$  the above equation takes the form

$$\nabla_X FV = F\nabla_X^\perp V \quad (20)$$

which implies that  $\nabla_X^\perp V \in FD^\perp$ , for any  $V \in FD^\perp$ . Also we have  $g(V, H) = 0$ , for  $V \in FD^\perp$ , then using this fact we derive

$$g(\nabla_X^\perp V, H) = -g(V, \nabla_X^\perp H) = 0. \quad (21)$$

The equation (21) gives  $\nabla_X^\perp H \in \mu \oplus \omega D_\theta$ .

Now, for any  $X \in D_\theta$ , we have

$$\bar{\nabla}_X FH = F\bar{\nabla}_X H,$$

using equation (15), we obtain

$$-Xg(H, FH) + \nabla_X^\perp FH = -FXg(H, H) + F\nabla_X^\perp H,$$

using the equation (4) above equation takes the form

$$\nabla_X^\perp FH = -fXg(H, H) - \omega Xg(H, H) + F\nabla_X^\perp H,$$

taking Inner product with  $\omega X \in \omega D_\theta$  and using the equation (12)

$$g(\nabla_X FH, \omega X) = -\sin^2 \theta \|H\|^2 \|X\|^2 + g(\omega \nabla_X^\perp H, \omega X).$$

Then from equation (12), the last term of right hand side is identically zero, thus the above equation becomes

$$g(\nabla_X FH, \omega X) + \sin^2 \theta \|H\|^2 \|X\|^2 = 0. \quad (22)$$

Therefore equation (22) has a solution if either  $H = 0$  i.e.,  $M$  is totally geodesic or the angle of slant distribution  $D_\theta$  is zero i.e.,  $M$  is semi-invariant submanifold.

Now for any  $Z \in D^\perp$ , by equation (10)

$$-f\nabla_Z Z = A_{\omega Z} Z + th(Z, Z).$$

Taking Inner product with  $W \in D^\perp$  the above equation takes the form

$$-g(f\nabla_Z Z, W) = g(A_{\omega Z} Z, W) + g(th(Z, Z), W).$$

As  $M$  is totally umbilical pseudo-slant submanifold, then above equation becomes

$$g(Z, W)g(H, FZ) + g(tH, W)\|Z\|^2 = 0. \quad (23)$$

The above equation has a solution if either  $H \in \mu$  or  $\dim D^\perp = 1$ .

Now, in the following theorem we will see the impact of parallelism of  $\omega$  on  $M$ .

**Theorem 3.** *Let  $M$  be a totally umbilical pseudo-slant submanifold of a Riemannian product manifold  $\bar{M}$  such that dimension of slant distribution  $D_\theta \geq 4$  and  $\omega$  is parallel, then  $M$  is either*

- (i) *extrinsic sphere.*
- (ii) *or anti-invariant submanifold.*

*Proof.* Since dimension of slant distribution  $D_\theta \geq 4$ , then we can choose a set of orthogonal vectors  $X, Y \in D_\theta$ , such that  $g(X, Y) = 0$ . Now from equation (18)(b), we have

$$F\bar{R}(X, Y)Z = \bar{R}(X, Y)FZ$$

for any  $X, Y, Z \in D_\theta$ . Replacing  $Z$  by  $fY$ , we obtain

$$F\bar{R}(X, Y)fY = \bar{R}(X, Y)FfY.$$

Using equation (4) and Theorem (2.1), the above equation takes the form

$$F\bar{R}(X, Y)fY = \cos^2 \theta \bar{R}(X, Y)Y + \bar{R}(X, Y)\omega fY. \quad (24)$$

On the other hand, since  $\omega$  is parallel, then we have

$$\bar{R}(X, Y)\omega fY = \omega \bar{R}(X, Y)fY. \quad (25)$$

Then by equations (24) and (25) we have

$$F\bar{R}(X, Y)fY = \cos^2 \theta \bar{R}(X, Y)Y + \omega \bar{R}(X, Y)fY. \quad (26)$$

Taking Inner product in equation (27) by  $N \in T^\perp M$ , we get

$$g(F\bar{R}(X, Y)fY, N) = \cos^2 \theta g(\bar{R}(X, Y)Y, N) + g(\omega \bar{R}(X, Y)fY, N),$$

using equation (4) the above equation reduced to

$$\cos^2 \theta g(\bar{R}(X, Y, Y, N) = 0. \quad (27)$$

Then, from equation (17), we derive

$$\cos^2 \theta g(Y, Y)g(\nabla_X^\perp H, N) - g(X, Y)g(\nabla_Y^\perp H, N) = 0.$$

Since  $X$  and  $Y$  are orthogonal vectors, then the above equation gives

$$\cos^2 \theta g(\nabla_X^\perp H, N)\|Y\|^2 = 0. \quad (28)$$

The equation (28) has a solution either  $\theta = \pi/2$  i.e.,  $M$  is anti-invariant or  $\nabla_X^\perp H = 0 \forall X \in D_\theta$ . By similar calculation for any  $X \in D^\perp$  we can obtain  $\nabla_X^\perp H = 0$ , hence  $\nabla_X^\perp H = 0$  for all  $X \in TM$  i.e., the mean curvature vector  $H$  is parallel to submanifold, i.e.,  $M$  is extrinsic sphere.

Now we are in position to prove our main theorem:

**Theorem 4.** *Let  $M$  be a totally umbilical pseudo-slant submanifold of a Riemannian product manifold  $\bar{M}$ . Then  $M$  is either*

- (i) *Totally geodesic or*
- (ii) *Semi-invariant or*

(iii)  $\dim D^\perp = 1$  or

(iv) *Extrinsic sphere.*

case (iv) holds if  $\omega$  is parallel and  $\dim M \geq 5$ (odd)

*Proof.* If  $H \in \mu$  then by Theorem 3.1  $M$  is either totally geodesic or semi-invariant submanifolds which are case (i) and (ii). If  $H \notin \mu$ , then equation (24) has a solution if  $\dim D^\perp = 1$  which is case (iii) and moreover if  $H \notin \mu$  and  $\omega$  is parallel on  $M$  then by Theorem 3.2  $M$  is extrinsic sphere which proves the theorem completely.

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Meraj Ali Khan  
Department of Mathematics,  
University of Tabouk  
K.S.A.  
email: *meraj79@gmail.com*

Falleh R. Al-Solamy  
Department of Mathematics,  
King Abdulaziz University, Jeddah  
K.S.A.  
email: *falleh@hotmail.com*

Amira A. Ishan  
Department of Mathematics  
Taif University  
Taif,  
Kingdom of Saudi Arabia  
email: *amiraishan@hotmail.com*