

## ON GENERALIZED PROBABILISTIC METRIC SPACES

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ABSTRACT. In the present paper we study some generalized probabilistic metric spaces. Relationships with another deterministic and probabilistic metric structures are analyzed. A contraction condition for mappings with values into such a generalized probabilistic metric space is given. Fixed point results are proved.

*Key words and phrases:* generalized probabilistic metric space, probabilistic contraction, fixed point.

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## 1. INTRODUCTION

In [11] K. Menger proposed a probabilistic concept of distance by replacing the number  $d(p, q)$ , the distance between points  $p, q$  by a distribution function  $F_{p,q}$ . This idea led to a large development of probabilistic analysis [2], [8] [12]. The idea of a  $n$ -dimensional metric has also appeared first in K. Menger's papers [10]. Three decades later S. Gähler formulated an appropriate system of axioms for a distance between three points and developed the theory of 2-metric spaces [5].

An enlargement of the concept of 2-metric space was given in [3], where a study of generalized metric spaces is developed.

Now, we recall some standard notions and notations. Let  $\mathbb{R}$  denotes the set of real numbers,  $\mathbb{R}_+ = \{x \in \mathbb{R} : x \geq 0\}$  and  $I = [0, 1]$  the closed unit interval. A mapping  $F : \mathbb{R} \rightarrow I$  is called a distribution function if it is non decreasing, left-continuous with  $\inf F = 0$  and  $\sup F = 1$ .

$D_+$  denotes the set of all distribution functions for that  $F(0) = 0$ . Let  $F, G$  be in  $D_+$ , then we write  $F \leq G$  if  $F(t) \leq G(t)$  for all  $t \in \mathbb{R}$ . If  $a \in \mathbb{R}_+$  then  $H_a$  will be the element of  $D_+$ , for which  $H_a(t) = 0$  if

$t \leq a$  and  $H_a(t) = 1$  if  $t > a$ . It is obvious that  $H_0 \geq F$ , for all  $F \in D_+$ . The set  $D_+$  will be endowed with the natural topology defined by the modified Lévy metric  $d_L$  [10]. The modified Levy metric  $d_L$  induces on  $D_+$  the topology of weak convergence, and the following properties are verified :

- (1)  $F(t) > 1 - t$  if and only if  $d_L(F, H_0) < t$ .
- (2) If  $F \leq G$  then  $d_L(G, H_0) \leq d_L(F, H_0)$ .
- (3) The metric space  $(D_+, d_L)$  is compact, and hence complete.

A t-norm  $T_1$  is a two place function  $T_1 : I \times I \rightarrow I$  which is associative, commutative, non decreasing in each place and such that  $T_1(a, 1) = a$ , for all  $a \in [0, 1]$ . A triangle function  $\tau_1$  is a binary operation on  $D_+$  which is commutative, associative and for which  $H_0$  is the identity, that is,  $\tau_1(F, H_0) = F$ , for every  $F \in D_+$  [2],[12].

In [3] B. C. Dhage formulated the following system of axioms for a distance between three points and developed a theory of generalized metric spaces.

**Definition 1.1.** *Let  $X$  be a non empty set. A generalized metric space is a pair  $(X, d)$ , where  $d$  is a mapping from  $X \times X \times X$  into  $\mathbb{R}_+$  and the following conditions are satisfied :*

- (4)  $d(x, y, z) = 0$  if and only if  $x = y = z$ .
- (5)  $d(x, y, z) = 0$  if at least two of  $x, y, z$  are equal.
- (6)  $d(x, y, z) = d(x, z, y) = d(y, z, x)$ , for every  $x, y, z$  in  $X$ .
- (7)  $d(x, y, z) \leq d(x, y, u) + d(x, u, z) + d(u, y, z)$ , for every  $x, y, z, u$  in  $X$ .

Geometrically, the 2-metric between three points defined in [5] measures the area of the triangle having as vertices these points, while the generalized metric defined in [3] measures the perimeter of the same triangle.

## 2. GENERALIZED PROBABILISTIC METRIC SPACES

Let  $T_1$  be a t-norm and let  $\tau$  be a triangle function. In the sequel we will use the functions  $T : [0, 1]^3 \rightarrow [0, 1]$  given by  $T(a, b, c) = T_1(T_1(a, b), c)$  and  $\tau : [D_+]^3 \rightarrow D_+$  given by  $\tau(F, G, H) = \tau_1(\tau_1(F, G), H)$ , we name  $T$  a th-norm and  $\tau$  a th-function.

They have appropriate properties for writing a triangle inequality in generalized probabilistic metric spaces. In [1] a generalized class of t-norms on  $[0, 1]^3$  was defined , but they are, in fact, th-norms.

**Definition 2.1.** *A generalized probabilistic metric space is an ordered triple  $(X, \mathcal{F}, \tau)$ , where  $X$  is a non empty set,  $\mathcal{F}$  is a function defined on  $X \times X \times X$  with values into  $D_+$ ,  $\tau$  is a th-function and the following conditions are satisfied:*

- (8)  $F_{x,y,z} = H_0$  if and only if  $x = y = z$ ,  
 (9)  $F_{x,y,z} = H_{x,z,y} = H_{y,z,x}$ , for every  $x, y, z$  in  $X$ .  
 (10)  $F_{x,y,z} \geq \tau(F_{x,y,u}, F_{x,u,z}, F_{u,y,z})$ , for every  $x, y, z, u$  in  $X$ .

The inequality (10), named and tetrahedral inequality can be given by a  $t$ -norm  $T$  by :

(11)  $F_{x,y,z}(t) \geq T(F_{x,y,u}(t_1), F_{x,u,z}(t_2), F_{u,y,z}(t_3))$ , for every  $t_1, t_2, t_3 \in \mathbb{R}_+$  such that  $t_1 + t_2 + t_3 = t$ . In this case  $(X, \mathcal{F}, T)$  is called a generalized Menger metric space.

It is easy to check that every generalized metric space  $(X, d)$  can be made, in a natural way, a generalized Menger metric space by setting  $F_{x,y,z}(t) = H_0(t - d(x, y, z))(t)$ , for every  $x, y, z \in X, t \in \mathbb{R}_+$  and  $T = \text{Min}$ .

The relationship between the two class of generalized metric spaces is given by the following statement.

**Proposition 2.2.** *If  $T$  is a left continuous  $t$ -norm and  $\tau_T$  is the  $t$ -function defined by  $\tau_T(F, G, H)(t) = \sup_{t_1+t_2+t_3 < t} T(F(t_1), G(t_2), H(t_3))$ ,  $t > 0$ , then  $(X, \mathcal{F}, \tau_T)$  is a probabilistic  $D$ -metric space if and only if  $(X, \mathcal{F}, T)$  is a Menger  $D$ -metric space.*

**Definition 2.3.** *A sequence  $\{x_n\}$  of points in a generalized probabilistic metric space  $(X, \mathcal{F}, \tau)$  is said to be convergent to the point  $x \in X$  if for each  $t > 0$  there exists  $n_0 \in \mathbb{N}$  such that*

$$F_{x_n, x_m, x}(t) > 1 - t,$$

for all  $n, m \geq n_0$ .

**Definition 2.4.** *We say that a sequence  $\{x_n\}$  of probabilistic  $D$ -metric space  $(X, \mathcal{F}, \tau)$  is a Cauchy sequence if for each  $t > 0$  there exists  $n_0 \in \mathbb{N}$  such that*

$$F_{x_n, x_m, x_p}(t) > 1 - t,$$

for all  $m, p > n \geq n_0$ .

**Definition 2.5.** *A generalized probabilistic metric space  $(X, \mathcal{F}, T)$  is said to be complete if every Cauchy sequence under the probabilistic metric  $\mathcal{F}$  converges to a point  $x \in X$*

**Definition 2.6.** *A self mapping  $f$  of a probabilistic  $D$ -metric space  $(X, \mathcal{F}, T)$  is said to be continuous if  $f x_n \rightarrow f x$ , whenever  $x_n \rightarrow x$ .*

**Proposition 2.7.** *Let  $\{x_n\}$  be a sequence of points in a generalized probabilistic metric space  $(X, \mathcal{F}, T)$   $T$  be a continuous  $t$ -norm  $T$ . Then we have:*

- (a)  $x_n \rightarrow x$ , if and only if  $d_L(F_{x_n, x_m, x}, H_0) \rightarrow 0$ ,  $(n, m \rightarrow \infty)$ .
- (b)  $x_n \rightarrow x$  if and only if  $F_{x_n, x_m, x}(t) \rightarrow H_0(t)$ , for all  $t > 0$ .
- (c)  $\{x_n\}$  is a Cauchy sequence if and only if  $d_L(F_{x_n, x_m, x_p}, H_0) \rightarrow 0$   
 $(n, m, p \rightarrow \infty)$ .
- (d)  $\{x_n\}$  is a Cauchy sequence if and only if  $F_{x_n, x_m, x_p}(t) \rightarrow H_0(t)$   
, for all  $t > 0$ .

**Example 2.8.** Let  $(L, \|\cdot\|)$  be a separable Banach space and let  $(L, \mathcal{B})$  be the measurable space, where  $\mathcal{B}$  is the  $\sigma$ -algebra of Borel subsets of the separable Banach space  $(L, \|\cdot\|)$ . We denote by  $X$  the linear space of all random variables defined on a probability measure space  $(\Omega, \mathcal{K}, P)$  with values in  $(L, \mathcal{B})$ . For all  $x, y, z \in X$ ,  $t \in \mathcal{R}$ , and  $t > 0$  we define the mapping  $\mathcal{F} : X^3 \rightarrow D_+$  given by  $\mathcal{F}(x, y, z) = F_{x, y, z}(t)$ , where

$$F_{x, y, z}(t) = P(\{\omega \in \Omega : \|x(\omega) - y(\omega)\| + \|x(\omega) - y(\omega)\| + \|y(\omega) - z(\omega)\| < t\}).$$

The triple  $(X, \mathcal{F}, T_m)$  becomes a generalized probabilistic metric space. The following theorem gives a relationship between a generalized probabilistic metric space and a probabilistic metric space.

**Theorem 2.9.** Let  $(X, \mathcal{F}, T)$  be a Menger space which has at least three points and let  $\mathcal{F} : X^3 \rightarrow D_+$  a mapping given by

$$\mathcal{F}(x, y, z) = F_{x, y, z}(t) = \text{Min}\{F_{x, y}(t), F_{y, z}(t), F_{z, x}(t)\},$$

then the triple  $(X, \mathcal{F}, \text{Min})$  is a generalized Menger space.

Now, we show that some generalized Menger spaces  $(X, \mathcal{F}, T)$  can be endowed with a generalized metric that induces the same convergence with the generalized probabilistic metric  $\mathcal{F}$ .

**Theorem 2.10.** Let  $(X, \mathcal{F}, T)$  be a generalized Menger space under a continuous  $t$ -norm  $T$  such that  $T \geq T_m$  and let consider the mapping  $d : X^3 \rightarrow \mathcal{R}$  defined by

$$d(x, y, z) = \sup\{\varepsilon \in [0, 1) : F_{x, y, z}(\varepsilon) \leq 1 - \varepsilon\}.$$

Then we have :

- (a)  $d(x, y, z) < t$  if and only if  $F_{x, y, z}(t) > 1 - t$ .
- (b)  $(X, d)$  is a generalized metric space.
- (c) The convergence under the generalized probabilistic metric  $\mathcal{F}$  is equivalent with convergence under the generalized metric  $d$ .

### 3. A FIXED POINT THEOREM IN A GENERALIZED PROBABILISTIC METRIC SPACE

A first type of contraction conditions in probabilistic metric spaces was first given [13], fixed point theorems were also obtained. Later a second type of contraction mappings was introduced in [9]. Since, many results were obtained [2],[8],[10]. In what sequel we study a type of contraction in generalized probabilistic metric spaces and we give a fixed point theorem.

Let us consider a function  $\varphi : \mathbf{R}_+ \rightarrow \mathbf{R}_+$  such that the following conditions are satisfied :

- (a<sub>1</sub>)  $\varphi$  is nondecreasing and right continuous;
- (a<sub>2</sub>)  $\lim_{n \rightarrow \infty} \varphi^n(t) = 0$ , for all  $t > 0$ ;
- (a<sub>3</sub>) there is  $t > 0$  such that  $\varphi(t) > 1$  ;

It is easy to see that under these conditions  $\varphi(t) < t$ . We denote by  $\Phi$  the set of all functions which satisfy the conditions (a<sub>1</sub>), (a<sub>2</sub>), and a<sub>3</sub>. The family of functions  $\varphi_{k,n}(t) = k^nt$ ,  $k \in (0, 1)$  and  $n \in \mathbf{N}$  is into the set  $\Phi$ . Now, let  $\varphi$  be in  $\Phi$ .

**Definition 3.1.** *Let  $(X, \mathcal{F}, T)$  be a generalized Menger space under a continuous th-norm  $T$ . A mapping  $f : X \rightarrow X$  which satisfies the following condition :*

$$(c) \text{ If } t > 0 \text{ and } F_{x,y,z}(t) > 1 - t, \text{ then } F_{fx,fy,fz}(\varphi(t)) > 1 - \varphi(t)$$

*is called  $\varphi$ -contraction.*

*The definition seems to be natural because we mean in a particular case that, under a probability measure, the perimeter of the triangle whose vertices are  $fx, fy, fz$  is less than the perimeter of the triangle whose vertices are  $x, y, z$ .*

**Theorem 3.2.** *Let  $(X, \mathcal{F}, T)$  be a generalized Menger space under a continuous th-norm  $T$ . Then a  $\varphi$ -contraction  $f : X \rightarrow X$  has a unique fixed point which is the limit of the sequence  $\{x_n\}$  defined by  $x_0 \in X$  and  $x_{n+1} = fx_n$ ,  $n \geq 0$ .*

By the above theorems fixed point results can be translated between probabilistic and deterministic generalized metric spaces.

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