

$G - N$ -QUASIGROUPS AND FUNCTIONAL EQUATIONS ON QUASIGROUPS

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ABSTRACT. Based on $G - n$ -quasigroups we give straightforward methods to solve the functional equations of generalized associativity, cyclic associativity and bisymmetry on quasigroups.

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In this paper we solve functional equations of generalized associativity (1), cyclic associativity (2) and bisymmetry (or mediality) (3).

$$\alpha_1(\alpha_2(x, y), z) = \alpha_3(x, \alpha_4(y, z)) \quad (1)$$

$$\alpha_1(x, \alpha_2(y, z)) = \alpha_3(y, \alpha_4(z, x)) = \alpha_5(z, \alpha_6(x, y)) \quad (2)$$

$$\alpha_1(\alpha_2(x, y), \alpha_3(z, u)) = \alpha_4(\alpha_5(x, z), \alpha_6(y, u)) \quad (3)$$

where x, y, z, u are taken from an arbitrary set A and α_i are quasigroup operations on A .

The method used is an example of the application of our results developed in [3].

All three equations have been investigated by Aczél, Belousov and Hosszú [1] and Belousov [2]. The used methods to solve these equations have an involved part: the proof that all quasigroups (A, α_i) are isotopic to the same group $(A, +)$. Our method reduces the proofs to a routine calculation.

For notions and notations see [3].

1. THE EQUATION OF GENERALIZED ASSOCIATIVITY

Theorem 1. *The set of all solutions of the functional equation of generalized associativity over the set of quasigroup operations on an arbitrary set A is described by the relations*

$$\begin{aligned} \alpha_1(x, y) &= F_1(x) + F_2(y), \alpha_2(x, y) = F_1^{-1}(F_3(x) + F_4(y)), \\ \alpha_3(x, y) &= F_3(x) + F_5(y), \alpha_4(x, y) = F_5^{-1}(F_4(x) + F_2(y)), \end{aligned} \quad (4)$$

where $(A, +)$ is an arbitrary group and F_1, \dots, F_5 are arbitrary substitutions of the set A .

Proof. It is obvious that all (A, α_i) defined by relations (4) are quasigroups isotopic to group $(A, +)$. Substituting these values of the functional variables in (1) we obtain for the both sides the same expression.

Conversely, let $\alpha_1, \dots, \alpha_4$ be four quasigroup operations on A and forming a solution of the functional equation (1). We define $\alpha : A^3 \rightarrow A$ by

$$\alpha(x, y, z) = \alpha_1(\alpha_2(x, y), z) = \alpha_3(x, \alpha_4(y, z)) \quad (5)$$

It is easy to prove that (A, α) is a 3-quasigroup. Moreover, cf. Theorem 6. [3] (A, α) is a G -quasigroup, i.e. $\alpha(x, y, z) = T_1(x) + T_2(y) + T_3(z)$, where $(A, +)$ is a group and T_i are translations by $a = (a_i^3) \in A^3$ in (A, α) . The zero element of $(A, +)$ is $0 = T_1(a_1) = T_2(a_2) = T_3(a_3)$.

Putting $z = a_3$ in (5) we obtain

$$\alpha_1(\alpha_2(x, y), a_3) = \alpha_3(x, \alpha_4(y, a_3)) = T_1(x) + T_2(y) \quad (6)$$

Since (A, α_1) and (A, α_4) are quasigroups, the mappings $f(x) = \alpha_1(x, a_3)$ and $g(x) = \alpha_4(x, a_3)$ are substitutions of A .

From (6) we get

$$\alpha_2(x, y) = f^{-1}(T_1(x) + T_2(y))$$

and

$$\alpha_3(x, y) = T_1(x) + T_2(g^{-1}(y)).$$

If in equality (5) we put $x = a_1$ then we get

$$\alpha_1(\alpha_2(a_1, y), z) = \alpha_3(a_1, \alpha_4(y, z)) = T_2(y) + T_3(z) \quad (7)$$

The mappings $h(x) = \alpha_2(a_1, x)$ and $u(x) = \alpha_3(a_1, x)$ are substitutions of A ((A, α_2) and (A, α_3) are quasigroups). Therefore, from (7) we have

$$\alpha_1(y, z) = T_2(h^{-1}(y)) + T_3(z)$$

and

$$\alpha_4(y, z) = u^{-1}(T_2(y) + T_3(z)).$$

Now, from

$$f(h(x)) = \alpha_1(h(x), a_3) = \alpha_1(\alpha_2(a_1, x), a_3) = \alpha(a_1, x, a_3) = T_2(x)$$

we obtain $T_2 \circ h^{-1} = f$ and from

$$u(g(x)) = \alpha_3(a_1, g(x)) = \alpha_3(a_1, \alpha_4(x, a_3)) = \alpha(a_1, x, a_3) = T_2(x)$$

we get $T_2 \circ g^{-1} = u$.

Taking into account the above results we have

$$\begin{aligned} \alpha_1(x, y) &= f(x) + T_3(y), & \alpha_2(x, y) &= f^{-1}(T_1(x) + T_2(y)), \\ \alpha_3(x, y) &= T_1(x) + u(y), & \alpha_4(x, y) &= u^{-1}(T_2(x) + T_3(y)). \end{aligned} \quad (8)$$

Thus, it follows from (8) that any solution of the equation (1) has the form (4).

2. THE EQUATION OF GENERALIZED CYCLIC ASSOCIATIVITY

Theorem 2. *The set of all solutions of the functional equation of generalized cyclic associativity over the set of quasigroup operations on an arbitrary set A is described by the relations*

$$\begin{aligned} \alpha_1(x, y) &= F_1(x) + F_2(y), & \alpha_2(x, y) &= F_2^{-1}(F_3(x) + F_4(y)), \\ \alpha_3(x, y) &= F_3(x) + F_5(y), & \alpha_4(x, y) &= F_5^{-1}(F_4(x) + F_1(y)), \\ \alpha_5(x, y) &= F_4(x) + F_6(y), & \alpha_6(x, y) &= F_6^{-1}(F_1(x) + F_3(y)) \end{aligned} \quad (9)$$

where $(A, +)$ is an arbitrary commutative group and F_1, \dots, F_6 are arbitrary substitutions of the set A .

Proof. Let $\alpha_1, \dots, \alpha_6$ be six quasigroup operations on A and forming a solution of equation (2). We define $\alpha : A^3 \rightarrow A$ by

$$\alpha(x, y, z) = \alpha_1(x, \alpha_2(y, z)) = \alpha_3(y, \alpha_4(z, x)) = \alpha_5(z, \alpha_6(x, y)) \quad (10)$$

It is obvious that (A, α) is a 3-quasigroup.

From $\alpha(x, y, z) = \alpha_1(x, \alpha_2(y, z))$ it follows immediately that condition $D_{2,3}$ holds in (A, α) , $\alpha(x, y, z) = \alpha_3(y, \alpha_4(z, x))$ implies that condition D_{1-3} holds in (A, α) and from $\alpha(x, y, z) = \alpha_5(z, \alpha_6(x, y))$ we obtain that condition $D_{1,2}$ holds in (A, α) . Therefore, cf. Theorem 9 [3] (A, α) is a G_a -quasigroup, i.e. $\alpha(x, y, z) = T_1(x) + T_2(y) + T_3(z)$, where $(A, +)$ is a commutative group, T_i are translations by an arbitrary element $a = (a_1^3) \in A^3$ in (A, α) and $T_1(a_1) = T_2(a_2) = T_3(a_3) = 0$ - zero element of $(A, +)$.

From (10), for $x = a_1$ we obtain

$$\alpha_1(a_1, \alpha_2(y, z)) = \alpha_3(y, \alpha_4(z, a_1)) = \alpha_5(z, \alpha_6(a_1, y)) = T_2(y) + T_3(z).$$

Therefore

$$\begin{aligned}\alpha_2(y, z) &= f^{-1}(T_2(y) + T_3(z)), & \text{where } f(x) &= \alpha_1(a_1, x), \\ \alpha_3(y, z) &= T_2(y) + T_3(g^{-1}(z)), & \text{where } g(x) &= \alpha_4(x, a_1), \\ \alpha_5(z, y) &= T_3(z) + T_2(h^{-1}(y)), & \text{where } h(x) &= \alpha_6(a_1, x).\end{aligned}$$

Putting $z = a_3$ in (10) we get

$$\alpha_1(x, \alpha_2(y, a_3)) = \alpha_5(a_3, \alpha_6(x, y)) = T_1(x) + T_2(y).$$

In consequence

$$\begin{aligned}\alpha_1(x, z) &= T_1(x) + T_2(u^{-1}(y)), & \text{where } u(x) &= \alpha_2(x, a_3), \\ \alpha_6(x, y) &= v^{-1}(T_1(x) + T_2(y)), & \text{where } v(x) &= \alpha_5(a_3, x).\end{aligned}$$

If in (10) we put $y = a_2$ then we obtain $\alpha_3(a_2, \alpha_4(z, x)) = T_1(x) + T_3(z)$ hence $\alpha_4(z, x) = w^{-1}(T_1(x) + T_3(z))$ where $w(x) = \alpha_3(a_2, x)$.

Now,

$$\begin{aligned}f(u(x)) &= \alpha_1(a_1, \alpha_2(x, a_3)) = T_2(x), & \text{i.e. } f &= T_2 \circ u^{-1}, \\ w(g(x)) &= \alpha_3(a_2, \alpha_4(x, a_1)) = T_3(x), & \text{i.e. } w &= T_3 \circ g^{-1} \text{ and} \\ v(h(x)) &= \alpha_5(a_3, \alpha_6(a_1, x)) = T_2(x), & \text{i.e. } v &= T_2 \circ h^{-1}.\end{aligned}$$

In conclusion,

$$\begin{aligned}\alpha_1(x, y) &= T_1(x) + f(y), & \alpha_2(x, y) &= f^{-1}(T_2(x) + T_3(y)) \\ \alpha_3(x, y) &= T_2(x) + w(y), & \alpha_4(x, y) &= w^{-1}(T_1(x) + T_3(y)), \\ \alpha_5(x, y) &= v(x) + T_3(y), & \alpha_6(x, y) &= v^{-1}(T_1(x) + T_2(y))\end{aligned} \quad (11)$$

Thus, it follows from (11) that any solution of the equation (2) has the form (9).

The converse is obvious.

3. THE EQUATION OF GENERALIZED BISYMMETRY

Theorem 3. *The set of all solutions of the functional equation of generalized bisymmetry over the set of quasigroup operations on an arbitrary set A is described by the relations*

$$\begin{aligned}\alpha_1(x, y) &= F_1(x) + F_2(y), & \alpha_2(x, y) &= F_1^{-1}(F_3(x) + F_4(y)), \\ \alpha_3(x, y) &= F_2^{-1}(F_5(x) + F_6(y)), & \alpha_4(x, y) &= F_7(x) + F_8(y), \\ \alpha_5(x, y) &= F_7^{-1}(F_3(x) + F_5(y)), & \alpha_6(x, y) &= F_8^{-1}(F_4(x) + F_6(y)),\end{aligned} \quad (12)$$

where $(A, +)$ is an arbitrary commutative group and F_1, \dots, F_8 are arbitrary substitutions of the set A .

Proof. Let $\alpha_1, \dots, \alpha_6$ be six quasigroup operations on A and forming a solution of equation (3). We define $a : A^4 \rightarrow A$ by

$$\alpha(x, y, z, u) = \alpha_1(\alpha_2(x, y), \alpha_3(z, u)) = \alpha_4(\alpha_5(x, z), \alpha_6(y, u)) \quad (13)$$

It is obvious that (A, α) is 4-quasigroup. According to Theorem 11 [3] (A, α) is a G_a -quasigroup, i.e.

$\alpha(x, y, z, u) = T_1(x) + T_2(y) + T_3(z) + T_4(u)$, where $(A, +)$ is a commutative group with zero element $0 = T_1(a_1) = T_2(a_2) = T_3(a_3) = T_4(a_4)$, T_i being translations by $a = (a_i^4) \in A^4$ in (A, α) .

Putting $z = a_3$ and $u = a_4$ in (13) we get

$$\alpha_1(\alpha_2(x, y), \alpha_3(a_3, a_4)) = \alpha_4(\alpha_5(x, a_3), \alpha_6(y, a_4)) = T_1(x) + T_2(y) \quad (14)$$

Since (A, α_1) , (A, α_5) and (A, α_6) are quasigroups the mappings $f(x) = \alpha_1(x, \alpha_3(a_3, a_4))$, $f_1(x) = \alpha_5(x, a_3)$ and $f_2(x) = \alpha_6(x, a_4)$ are substitutions of the set A . From (14) we obtain $\alpha_2(x, y) = f^{-1}(T_1(x) + T_2(y))$ and $\alpha_4(x, y) = T_1(f_1^{-1}(x)) + T_2(f_2^{-1}(y))$. For $x = a_1$ and $y = a_2$ in (13) we have

$$\alpha_1(\alpha_2(a_1, a_2), \alpha_3(z, u)) = T_3(z) + T_4(u)$$

and thus

$$\alpha_3(z, u) = g^{-1}(T_3(z) + T_4(u)), \quad \text{where } g(x) = \alpha_1(\alpha_2(a_1, a_2), x).$$

If we put $y = a_2$ and $z = a_3$ in (13) then we get

$$\alpha_1(\alpha_2(x, a_2), \alpha_3(a_3, u)) = T_1(x) + T_4(u)$$

Hence $\alpha_1(x, u) = T_1(g_1^{-1}(x)) + T_4(g_2^{-1}(u))$. Putting $y = a_2$ and $u = a_4$ in (13) we obtain $\alpha_4(\alpha_5(x, z), \alpha_6(a_2, a_4)) = T_1(x) + T_3(z)$ and then $\alpha_5(x, z) = h^{-1}(T_1(x) + T_3(z))$ where $h(x) = \alpha_4(x, \alpha_6(a_2, a_4))$.

Finally, if we put $x = a_1$ and $z = a_3$ in (13) then we have

$$\alpha_4(\alpha_5(a_1, a_3), \alpha_6(y, u)) = T_2(y) + T_4(u)$$

and thus $\alpha_6(y, u) = h_1^{-1}(T_2(y) + T_4(u))$ for $h_1(x) = \alpha_4(\alpha_5(a_1, a_3), x)$.

Now, $f(g_1(x)) = \alpha_1(g_1(x), \alpha_3(a_3, a_4)) = \alpha_1(\alpha_2(x, a_2), \alpha_3(a_3, a_4)) = T_1(x)$
 implies that $T_1 \circ g_1^{-1} = f$,

$$g(g_2(x)) = \alpha_1(\alpha_2(a_1, a_2), g_2(x)) = \alpha_1(\alpha_2(a_1, a_2), \alpha_3(a_3, x)) = T_4(x)$$

implies that $T_4 \circ g_2^{-1} = g$,

$$h(f_1(x)) = \alpha_4(f_1(x), \alpha_6(a_2, a_4)) = \alpha_4(\alpha_5(x, a_3), \alpha_6(a_2, a_4)) = T_1(x)$$

implies that $T_1 \circ f_1^{-1} = h$ and

$$h_1(f_2(x)) = \alpha_4(\alpha_5(a_1, a_3), f_2(x)) = \alpha_4(\alpha_5(a_1, a_3), \alpha_6(x, a_4)) = T_2(x)$$

implies that $T_2 \circ f_2^{-1} = h_1$.

Taking into account the above results we have

$$\begin{aligned} \alpha_1(x, y) &= f(x) + g(y), & \alpha_2(x, y) &= f_1^{-1}(T_1(x) + T_2(y)), \\ \alpha_3(x, y) &= g^{-1}(T_3(x) + T_4(y)), & \alpha_4(x, y) &= h(x) + h_1(y), \\ \alpha_5(x, y) &= h^{-1}(T_1(x) + T_3(y)), & \alpha_6(x, y) &= h_1^{-1}(T_2(x) + T_4(y)). \end{aligned} \quad (15)$$

Thus, it follows from (15) that any solution of the equation (3) has the form (12).

The converse is clear.

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